# Common Fixed Point Theorems for Co-Cyclic Weak Contractions in Compact Metric

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Abstract—In this paper, we prove some common fixed point theorems for co-cyclic weak contractions in compact metric spaces.

*Keywords*—Cyclic weak contraction, Co-cyclic weak contraction, Co-cyclic representation, Common fixed point.

### I. INTRODUCTION

A LBER and Guerre-Delabriere in [2] defined weakly contractive mappings and they proved some fixed point theorems in the Hilbert spaces. In [10], Rhoades extended some results of [2] to complete metric spaces.

Beg et. al. [4] and Babu et. al. [3] proved common fixed point theorems for a pair of weakly contractive map in complete metric space.

In 2003, Kirk et. al. [9] introduced the notion of Cyclic contraction and established some related fixed point theorems for mappings satisfying such contraction conditions. Suggested by the consideration in [9], Rus [11] introduced the following concept of cyclic representation and proved some fixed point theorems.

**Definition** 1: [11] Let X be a nonempty set, m a positive integer and  $T: X \to X$  a selfmap.  $X = \bigcup_{i=1}^{m} A_i$  is said to be a cyclic representation of X with respect to the map T if the following conditions hold:

1)  $A_i, i = 1, 2, \cdots, m$  are nonempty subsets of X;

2)  $T(A_1) \subset A_2, \cdots, T(A_{m-1}) \subset A_m, T(A_m) \subset A_1.$ 

In [8], Karapinar proves a fixed point theorem for a mapping T defined on a complete metric space X when X has a cyclic representation with respect to T.

**Example** 1: [5] Let  $X = [0,2], A_1 = [0,1], A_2 = [\frac{1}{2}, \frac{3}{2}]$ and  $A_3 = [1,2]$ . Now, we define a selfmap T on X by

$$T(x) = \begin{cases} x + \frac{1}{2} & \text{if } x \in [0, \frac{1}{2}] \\ 1 & \text{if } x \in (\frac{1}{2}, \frac{3}{2}] \\ x - 1 & \text{if } x \in (\frac{3}{2}, 2] \end{cases}$$

Then we observe that  $T(A_1) = \begin{bmatrix} \frac{1}{2}, 1 \end{bmatrix} \subset \begin{bmatrix} \frac{1}{2}, \frac{3}{2} \end{bmatrix} = A_2$ ,  $T(A_2) \subset \begin{bmatrix} 1, 2 \end{bmatrix} = A_3$  and  $T(A_3) = \begin{pmatrix} \frac{1}{2}, 1 \end{bmatrix} \subset \begin{bmatrix} 0, 1 \end{bmatrix} = A_0$ . Therefore,  $X = \bigcup_{i=1}^3 A_i$  is a cyclic representation of X with respect to T.

Throughout this paper, we denote  $R_+ = [0, \infty)$  and

$$\mathfrak{J} = \{\varphi \mid \varphi : R_+ \to R_+ \text{ is nondecreasing},\$$

$$\varphi(0) = 0, \ \varphi(t) > 0 \text{ for } t > 0 \}.$$

Recently, Harjani et.al. [6] established the following fixed point theorem for a continuous selfmap.

Alemayehu Geremew Negash is with the Department of Mathematics, College of Natural Sciences, Jimma University, Jimma, P.O. Box 378, Ethiopia; (e-mail: alemg1972@gmail.com). **Theorem** 1: Let (X, d) be a compact metric space and  $T : X \to X$  a continuous operator. Suppose that m is a positive integer,  $A_1, A_2, \dots, A_m$  nonempty subsets of  $X, X = \bigcup_{i=1}^m A_i$  satisfying

- X = ∪<sup>m</sup><sub>i=1</sub>A<sub>i</sub> is a cyclic representation of X with respect to T;
- 2)  $d(Tx,Ty) \leq d(x,y) \varphi(d(x,y))$  for any  $x \in A_i$  and  $y \in A_{i+1}$ , where  $\varphi \in \mathfrak{J}$ .

Then T has a unique fixed point.

Note that to guarantee the existence and uniqueness of common fixed points of a pair of maps, we need an additional condition, called weak compatibility, which is defined as follows.

**Definition** 2: [7] Let X be a nonempty set. Two selfmaps  $S, T : X \to X$  are said to be weakly compatible if they commute at their coincidence points, i.e., if  $x \in X$  such that Sx = Tx, then STx = TSx.

The purpose of this paper is to establish a common fixed point theorem for a co-cyclic weak contraction defined in compact metric spaces. Our result extends the result of Harjani et. al. [6] to a co-cyclic weak contraction.

#### II. PRELIMINARIES

**Definition** 3: [5] Let X be a nonempty set, m a positive integer and T,  $f: X \to X$  be two selfmaps.  $X = \bigcup_{i=1}^{m} A_i$  is said to be a co-cyclic representation of X between f and T if the following conditions are satisfied:

- 1)  $A_i, i = 1, 2, \dots, m$  are nonempty subsets of X;
- 2)  $T(A_1) \subset f(A_2), \cdots, T(A_{m-1}) \subset f(A_m), and$  $T(A_m) \subset f(A_1).$

**Example** 2: Let X = [0, 1], and  $A_1 = [0, \frac{1}{2}]$  and  $A_2 = [\frac{1}{2}, 1]$ . We define a selfmap T and f on X by

$$T(x) = \begin{cases} x + \frac{1}{2} & \text{if } x \in [0, \frac{1}{2}] \\ 1 - x & \text{if } x \in (\frac{1}{2}, 1] \end{cases}$$

and

$$f(x) = \begin{cases} x & \text{if } x \in [0, \frac{1}{2}] \\ 2x - 1 & \text{if } x \in (\frac{1}{2}, 1] \end{cases}$$

Then we observe that  $T(A_1) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, 1 \in [0, 1] = f(A_2),$  $T(A_2) = \begin{bmatrix} 0, \frac{1}{2} \end{bmatrix} = f(A_1).$  Therefore,  $X = \bigcup_{i=1}^2 A_i$  is a co-cyclic representation of X between f and T.

We now introduce the following definitions.

**Definition** 4: Let (X, d) be a metric space, m is a positive integer,  $A_1, A_2, \dots, A_m$  a closed nonempty subsets of X, and  $X = \bigcup_{i=1}^{m} A_i$ . An operator  $T: X \to X$  is said to be co-cyclic weak contraction if there is an operator  $f: X \to X$  such that

- X = ∪<sup>m</sup><sub>i=1</sub>A<sub>i</sub> is a cyclic representation of X between f and T;
- 2)  $d(Tx, Ty) \leq d(fx, fy) \varphi(d(fx, fy))$  for any  $x \in A_i$ and  $y \in A_{i+1}$ , where  $A_{m+1} = A_1$  and  $\varphi \in \mathfrak{J}$ .

The purpose of this paper is to prove the following theorem.

## III. MAIN RESULTS

**Theorem 2:** Let (X, d) be a compact metric space and  $f, T: X \to X$  be two operators. Suppose that m is a positive integer,  $A_1, A_2, \dots, A_m$  are nonempty subsets of X, and  $X = \bigcup_{i=1}^m A_i$  satisfying

- 1)  $X = \bigcup_{i=1}^{m} A_i$  is a co-cyclic representation of X between f and T;
- 2)  $d(Tx,Ty) \leq d(fx,fy) \varphi(d(fx,fy))$  for any  $x \in A_i$ and  $y \in A_{i+1}$ , where  $A_{m+1} = A_1$  and  $\varphi \in \mathfrak{J}$ .

If the pair of operators (f, T) are weakly compatible on X, then f and T have a unique common fixed point in X.

**Proof.** Let  $x_0 \in X$ . Since  $T(A_i) \subset f(A_{i+1})$  for each  $i = 1, 2, \dots, m-1$  and  $T(A_m) \subset f(A_1)$ , there exists  $x_1 \in X$  such that  $Tx_0 = fx_1$ . On continuing the process, inductively we get a sequence  $x_n$  in X such that  $Tx_n = fx_{n+1}$  for each  $n = 0, 1, 2, \dots$ .

If there exists  $n_0 \in \mathbb{N}$  with  $Tx_{n_0+1} = Tx_{n_0} = fx_{n_0+1}$ and, thus, f and T have coincidence point  $x_{n_0+1}$ .

Suppose that  $x_{n+1} \neq x_n$  for all  $n = 0, 1, 2, \cdots$ . We now show that the sequence  $\{d(fx_n, fx_{n+1})\}$  is a nonincreasing sequence. By (1) of Theorem 3.1, for each n > 0 there exists  $i_n \in \{1, 2, \cdots, m\}$  such that  $x_{n-1} \in A_{i_n-1}$  and  $x_n \in A_{i_n}$ and using (2) of Theorem 1, we get

$$d(fx_n, fx_{n+1}) = d(Tx_{n-1}, Tx_n)$$
  

$$\leq d(fx_{n-1}, fx_n) - \varphi(d(fx_{n-1}, fx_n))$$
  

$$\leq d(fx_{n-1}, fx_n)$$
(1)

for each  $n = 1, 2, \cdots$ . Therefore,

$$d(fx_n, fx_{n+1}) \le d(fx_{n-1}, fx_n)$$
(2)

for all  $n \ge 0$ . Hence  $\{d(fx_n, fx_{n+1})\}$  is a non-increasing sequence of nonnegative reals and hence converges to a limit  $l \ge 0$ . Letting  $n \to \infty$  in (1), we obtain

$$l \le l - \lim_{n \to \infty} \varphi(d(fx_n, fx_{n+1})) \le l$$

and, hence

$$\lim_{n \to \infty} \varphi(d(fx_n, fx_{n+1})) = 0 \tag{3}$$

We claim that l = 0. Suppose l > 0. Since  $l = \inf \{ d(fx_n, fx_{n+1}) : n \in \mathbb{N} \},\$ 

$$0 < l \le d(fx_n, fx_{n+1})$$

for  $n = 0, 1, 2, \cdots$  and since  $\varphi$  is nondecreasing and  $\varphi(t) > 0$ for  $t \in (0, \infty)$ , we obtain

$$0 < \varphi(l) \le \varphi(d(fx_n, fx_{n+1}))$$

for  $n = 0, 1, 2, \dots$ , and hence letting  $n \to \infty$ , we get

$$0 < \varphi(l) \le \lim_{n \to \infty} \varphi(d(fx_n, fx_{n+1}))$$

which is a contradiction to (3). Therefore, l = 0. Hence,

$$\lim_{n \to \infty} d(fx_n, fx_{n+1}) = 0 \tag{4}$$

Since  $Tx_n = fx_{n+1}$  for each  $n = 1, 2, \dots$ , from (4) it follows that

$$\inf\{d(fx, Tx) : x \in X\} = 0.$$
 (5)

Now since the mapping  $X \mapsto \mathbb{R}^+$  defined by  $x \mapsto d(fx, Tx)$  is continuous and X is compact, we find  $u \in X$  such that

$$d(fu, Tu) = \inf\{d(fx, Tx) : x \in X\}.$$

By (5), d(fu, Tu) = 0 and, consequently, fu = Tu = z (say), which shows that the pair (f, T) has a point of coincidence. Since the pair (f, T) is weakly compatible,

$$Tz = Tfu = fTu = fz.$$

Hence,

$$Tz = fz. (6)$$

We claim that z = Tz. Suppose  $z \neq Tz$ . Then,

$$\begin{aligned} (z,Tz) &= d(Tu,Tz) \\ &\leq d(fu,fz) - \varphi(d(fu,fz)) \\ &\leq d(z,Tz) - \varphi(d(z,Tz)), \end{aligned}$$

which shows that

But

Hence,

$$\varphi(d(z, Tz)) \le 0.$$

 $\varphi(d(z,Tz)) = 0$ 

$$\varphi(d(z, Tz)) \ge 0.$$

Hence,

and since  $\varphi \in \mathfrak{J}$ , we have

d(z,Tz) = 0.

Tz = z.

Hence, by (6), we obtain

$$fz = Tz = z.$$

For the uniqueness part, suppose that z and w are common fixed points of f and T. Since  $X = \bigcup_{i=1}^{m} A_i$  is co-cyclic representation of X between f and T, we have  $z, w \in \bigcap_{i=1}^{m} A_i$ . By (2), we have

$$\begin{split} d(z,w) &= d(Tz,Tw) \leq d(fz,fw) - \varphi(d(fz,fw)) \\ &\leq d(z,w) - \varphi(d(z,w)) \end{split}$$

Therefore,

$$\varphi(d(z,w)) = 0.$$

Since  $\varphi \in \mathfrak{J}$ , d(z, w) = 0 and hence, z = w.

Since the identity map  $I_X$  defined on X is weakly

compatible with any selfmap T defined on X, if we choose  $f = I_X$ , the identity map on X, we obtain the following result: **Corollary** 1: Let (X, d) be a compact metric space and  $T: X \to X$  be an operator. Suppose that m is a positive integer,  $A_1, A_2, \dots, A_m$  are nonempty subsets of X, and  $X = \bigcup_{i=1}^m A_i$  satisfying

- X = ∪<sup>m</sup><sub>i=1</sub>A<sub>i</sub> is a cyclic representation of X with respect to T;
- 2)  $d(Tx,Ty) \leq d(x,y) \varphi(d(x,y))$  for any  $x \in A_i$  and  $y \in A_{i+1}$ , where  $A_{m+1} = A_1$  and  $\varphi \in \mathfrak{J}$ .

Then T has a unique fixed point in X.

**Proof.** Follows from Theorem 1 by choosing  $f = I_X$ .

**Remark** In the proof of Theorem 2.1 of [6], the authors do not use the continuity assumption of the map T. Also, we observe that Theorem 1 extends Theorem 2.1 of [6] to co-cyclic weak contraction.

**Definition** 5: [1] Let (X, d) be a metric space, and  $\mathfrak{T}$  be a set of selfmappings of X. The common fixed points of the set  $\mathfrak{T}$  is said to be well-posed if:

- ℑ has a unique common fixed point in X (That is, z is the unique point in X such that Tz = z for all T ∈ ℑ);
- 2) For every sequence  $\{z_n\}$  in X such that

$$\lim_{n \to \infty} d(z_n, \ T z_{n+1}) = 0, \forall T \in \mathfrak{T},$$

we have

$$\lim_{n \to \infty} d(z_n, \ z) = 0.$$

Our second result is concerned with the well-posedness of the common fixed point problem for two mappings f and T satisfying the inequality (2) of Theorem 1.

**Theorem 3:** Under the assumptions of Theorem 1, the common fixed point problem for f and T is well-posed; that is, if there is a sequence  $\{z_n\}$  in X with  $d(z_n, Tz_n) \to 0$  and  $d(z_n, fz_n) \to 0$  as  $n \to \infty$ , then  $z_n \to z$  as  $n \to \infty$ , where z is the unique common fixed point of f and T (whose existence is guaranteed by Theorem 1).

**Proof.** By Theorem 1, f and T have a unique common fixed point z. As z is common fixed point of f and T, by (2) of Theorem 1,  $z \in \bigcap_{i=1}^{m} A_i$ . Let  $\{z_n\}$  be a sequence in X such that  $d(z_n, Tz_n) \to 0$  and  $d(z_n, fz_n) \to 0$  as  $n \to \infty$ . Now consider

$$d(z, Tz_n) \le d(z, fz_n) - \varphi(d(z, fz_n)) \tag{7}$$

$$\leq d(z, z_n) + d(z_n, fz_n) - \varphi(d(z, fz_n)) \tag{8}$$

Also, from the triangle inequality, (2) of Theorem 1, Equation (8) and the fact that  $z \in \bigcap_{i=1}^{m} A_i$ , we have

$$d(z, z_n) \le d(z, Tz_n) + d(Tz_n, z_n)$$

$$\le d(z, z_n) + d(z_n, fz_n)$$

$$-\varphi(d(z, fz_n)) + d(Tz_n, z_n)$$
(9)

which implies

$$\varphi(d(z, fz_n)) \le d(z_n, fz_n) + d(Tz_n, z_n) \to 0$$

as  $n \to \infty$ . Hence,

$$\lim_{n \to \infty} \varphi(d(fz_n, z)) = 0.$$
(10)

We now claim that  $\lim_{n\to\infty} d(fz_n, z) = 0$ . Suppose not. Then there exists  $\varepsilon \ge 0$  such that for any  $n \in \mathbb{N}$  we can find  $k_n \ge n$  with  $d(fz_{k_n}, z) \ge \varepsilon$ . Since  $\varphi \in \mathfrak{J}$  is nondecreasing and  $\varphi(t) > 0$  for  $t \in (0, \infty)$ , we have

$$0 < \varphi(\varepsilon) \le \varphi(d(fz_{k_n}, z)). \tag{11}$$

Letting  $n \to \infty$  in (11)

$$0 < \varphi(\varepsilon) \le \lim_{n \to \infty} \varphi(d(fz_{k_n}, z)).$$

which contradicts (10). Therefore,

$$\lim_{n \to \infty} d(fz_n, \ z) = 0$$

and hence letting  $n \to \infty$  in (7), we obtain

$$\lim_{n \to \infty} d(z, \ Tz_n) = 0 \tag{12}$$

Consequently, letting  $n \to \infty$  in (9), using (12) we obtain

$$\lim_{n \to \infty} d(z_n, \ z) = 0$$

Hence the common fixed point problem of f and T is well-posed.

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